

## R&D NETWORKS

by **Sanjeev Goyal** and **José Luis Moraga-González**  
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### Supplementary Appendix

**Proof of Proposition 6** (the general  $\gamma$  case): We first consider the instability of the empty network. A comparison between equilibrium (A2) and deviating profits for general values of  $\gamma$  requires computing equilibrium profits for an interior Nash equilibrium. Solving the set of best-replies given in the main body of the text yields

$$e_i(g^e + g_{ij}) = \frac{(a - \bar{c})(n - 1)(\gamma(n + 1) - n)}{\gamma^2(n + 1)^3 - \gamma(2n^3 + n^2 + n + 2) + 2n(n - 1)}$$

$$e_l(g^e + g_{ij}) = \frac{(a - \bar{c})n[\gamma(n + 1) - 2(n - 1)]}{\gamma^2(n + 1)^3 - \gamma(2n^3 + n^2 + n + 2) + 2n(n - 1)}$$

Note that  $e_l(g^e + g_{ij}) > 0$  if and only if the condition  $\gamma > 2(n - 1)/(n + 1)$  holds. Plugging these efforts into (A3) yields:

$$\pi_i(g^e + g_{ij}) = \frac{(a - \bar{c})^2 \gamma [\gamma(n + 1) - n]^2 [\gamma(n + 1)^2 - (n - 1)^2]}{[\gamma^2(n + 1)^3 - \gamma(2n^3 + n^2 + n + 2) + 2n(n - 1)]^2} \quad (1)$$

With the help of software Mathematica 3.0 we can compare (1) and (A2) for general values of  $\gamma$ . Figure 1 depicts  $\pi(g^e) - \pi_i(g^e + g_{ij})$  for  $n \in [4, 30]$  and  $\gamma \in [2, 100]$ .<sup>1</sup> Upon the observation of this graph one sees that the empty network is generally not stable.

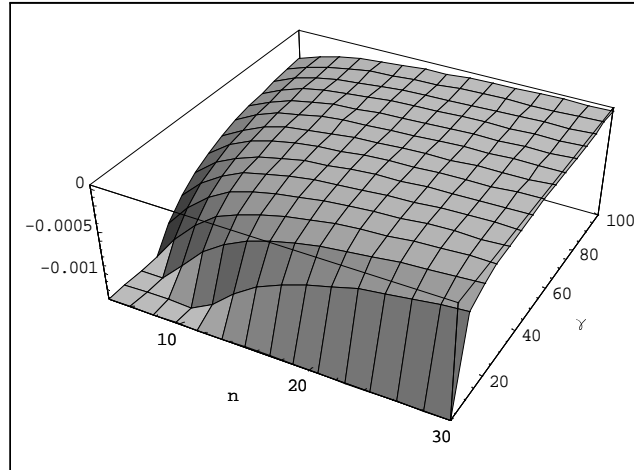


Figure 1:  $\pi(g^e) - \pi_i(g^e + g_{ij})$

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<sup>1</sup>Plotting  $\pi(g^e) - \pi_i(g^e + g_{ij})$  rather than  $\pi_i(g^e + g_{ij}) - \pi(g^e)$  allows for a better visualization.

We now consider the stability of the complete network. A comparison between (A5) and (A6) for general values of  $\gamma$  can be done with the help of Mathematica 3.0. Figure 2 exhibits the difference  $\pi_i(g^{n-1} - g_{ij}) - \pi(g^{n-1})$  for  $\gamma \in [4/25, 100]$  and  $n \in [4, 30]$ .<sup>2</sup> The graph suggests that the complete network is stable in general.

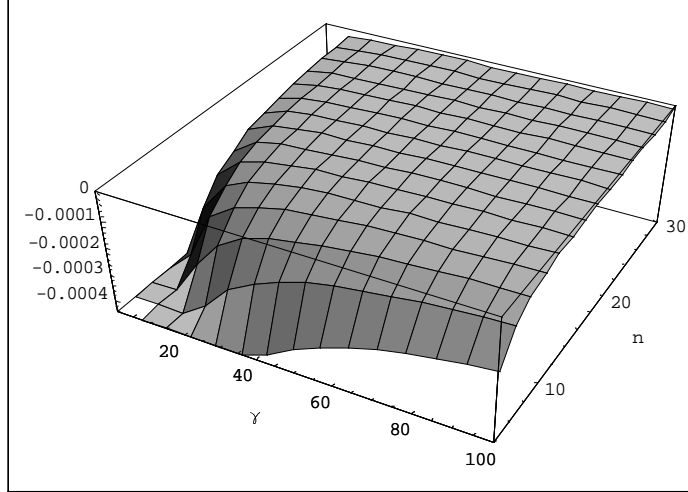


Figure 2:  $\pi_i(g^{n-1} - g_{ij}) - \pi(g^{n-1})$

△

**Proof of Proposition 9:** Consider first the complete network  $g^c$ . The stability condition (i) is trivially satisfied because there are no links to be formed. Thus,  $g^c$  is stable if and only if no firm has a unilateral interest in breaking one of its ties (stability condition (ii)). To prove this, consider a firm in  $g^c$  that deviates by severing a link. Note that the resulting collaboration network is the star network  $g^s$ , and also that the deviating firm becomes a spoke firm in  $g^s$ . Then, the profits such firm would attain from this deviation would be given by  $\pi_s(g^s)$  in (A10). We need to establish a comparison between equilibrium profits  $\pi(g^c)$  in (A7), and deviating benefits  $\pi_s(g^s)$ . Since the mathematical formulae for this comparison are lengthy, we have chosen to compare them by means of Figure 5 (given in the paper). In this graph we have represented the different profits obtained by the distinct firms in the different networks of collaboration (we have normalized  $a - \bar{c} = 1$ , without loss of generality). It can be seen that the curve  $\pi_s(g^s)$  lies below  $\pi(g^c)$  for all spillover parameters  $\beta$ , which shows that no firm in the complete network would like to sever a link. Observe that this also proves that the star network is not stable.

Consider now the partially connected network  $g^p$ . To see that the stability condition (i) is satisfied, let us check that no linked firm in  $g^p$  can gain by breaking its tie. Notice that if a linked firm severs its link, the resulting network is the empty network  $g^e$ . The deviator would obtain profits  $\pi(g^e)$  in (A16). We need to compare the profits  $\pi_l(g^p)$  in (A15) with  $\pi(g^e)$ . Let us again resort to Figure 5 in the paper for this profits

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<sup>2</sup>We have plotted  $\pi_i(g^{n-1} - g_{ij}) - \pi(g^{n-1})$  rather than  $\pi(g^{n-1}) - \pi_i(g^{n-1} - g_{ij})$  to improve visualization.

comparison. It is clearly seen that  $\pi(g^e)$  lies below  $\pi_l(g^p)$  for all  $\beta$ . Therefore, no firm in  $g^p$  has an unilateral incentive to break its collaborative link. Notice that this argument also proves that the empty network  $g^e$  is not stable because any pair of firms would deviate by forming a collaborative arrangement.

Let us now examine when stability condition (ii) is satisfied too. Notice first that the isolated firm always wishes to form a collaboration link with one of the linked firms in  $g^p$ . Indeed, if such a link is formed, then the isolated firm becomes a spoke firm in  $g^s$ , with profits  $\pi_s(g^s)$  in (A10). In  $g^p$  the isolated firm obtains equilibrium benefits  $\pi_i(g^p)$ . To compare these two profits, we use Figure 5 again. The graph shows that the curve  $\pi_i(g^p)$  lies below  $\pi_s(g^s)$  for all  $\beta$ . This shows that the isolated firm in  $g^p$  always wishes to form a collaboration.

However, since links are pair-wise in our model of networks, we have to check whether or not a linked firm in  $g^p$  desires to form a link with the isolated firm. Notice that if the linked is formed, the resulting network is the star network  $g^s$ , and that the deviating firm would be at the hub of the network. Thus, we have to compare equilibrium profits  $\pi_l(g^p)$  in (A14) with deviating profits  $\pi_h(g^s)$  in (A11). Figure 5 shows that these two curves intersect approximately at the point  $\beta_1 = 0.03649165$ , and that deviating profits curve  $\pi_h(g^s)$  lies thereafter below the equilibrium profits curve  $\pi_l(g^p)$ . This completes the proof.

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